Sample IOLab

# An Online Lab Section with IOLab and Remotely Operated Experiments

## Takashi Sato & Jillian Lang

Dept. of Physics, Kwantlen Polytechnic University, Vancouver, Canada



#### The Course

PHYS 1100 is a one-semester algebrabased course with mechanics and E & M.

#### Our Pilot (Winter 2017)

Students took regular, on-campus class

- on-campus lab sections (as usual), or
- online lab section (new)

#### Online Labs (9 total)

- 7 using IOLab
- · 2 remotely operated
- content & sequence paralleled oncampus sections

#### Pre-lab Assignment

- Available Sunday, due Wednesday
- · Equips students with theory, orientation and analysis tools

#### Lab Experiment & Report

- Available upon pre-lab submission, due Sunday midnight\*
- Students make prediction, perform experiment, write discussion incl. uncertainty

#### Learning Progression

#### Early Labs

Cyc

- · Student lab reports are heavily guided Later Labs
- progressively freer in format
- progression in student expectations

	Students explore motion in one dimension and its graphical representation.	IOLab	Explore x(t) graphs of objects in motion     Install the IOLab software on own device     Explore the basic functions/sensors of IOLab	Given sketches of x(t) graphs  1. reproduce graphs by moving IOLab accordingly.	Connecting physical motion to its graphical representation and vice versa.
	Students explore how position and velocity change with time for various types of motion in 1D.	IOLab	Match a described motion with x(t) and v(t) graphs     Introduction to measurement uncertainties and their propagation	Students push the IOLab up a ramp to 1. produce x(t) and v(t) graphs 2. determine the acceleration and ramp angle	Comparing obtained graphs with prediction. Start work with uncertainties.
	Students send IOLab in freefall. Graphical analysis yields g.	IOLab	Tutorial on data tables, graphing with error bars and interpreting linear graphs     Setting up the freefall experiment with IOLab	Drop IOLab onto a cushion from different heights     Measure time of freefall using accelerometer to plot a graph whose slope is predicted to be g/2	Constructing data tables Graphing with error bars Interpreting linear graphs
	Students launch IOLab over edge of table.	IOLab	Explore projectile motion from a horizontal platform using a simulation     Prepare and practice launching IOLab from table while taking data	Predict projectile range from table height and IOLab's speed at launch     Measure range from landing location	Uncertainty propagation Do measured result and prediction agree within uncertainty?
Acceleration on an Incline	Students roll cart down inclined track using remote control.	remote	Simulation assisted tutorial to derive "a = g sin θ", with uncertainties     Tutorial on operation of remote equipment	Predict acceleration from height and length of track     Measure acceleration from slope of v(t) graph	Uncertainty propagation Do measured result and prediction agree within uncertainty?
	Students swing IOLab around in circle on a string while force sensor measures tension.	IOLab	Simulation assisted tutorial on uniform circular motion     Tutorial on using IOLab force sensor	Measure period and radius to calculate speed, centripetal acceleration and force.     Measure centripetal force using force sensor	Uncertainty propagation Do measured result and prediction agree within uncertainty?
	Students bounce IOLab cart w/ spring bumper off a solid object.	IOLab	Students prepare and practice the collision while taking data	Change in velocity is compared to the area under F(t) graph	Interpreting v(t) and F(t) graphs for momentum and impulse
Conservation of Mechanical Energy	Students roll IOLab as a roller coaster.	IOLab	Roller coaster simulation, with friction     Students prepare a roller coaster-like track for IOLab	IOlab is sent down track and 1. calculate total energy from height and speed data	Performing relevant calculation and comparisons with minimal guidance

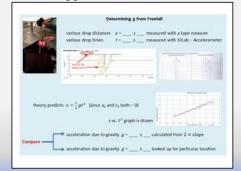
mode Pre-lab activity

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Physics

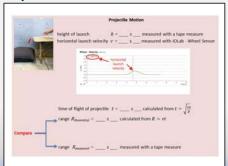
This pre-lab is longer than most and

		representation.		3. Explore the basic functions/sensors or local			
2		Students explore how position and velocity change with time for various types of motion in 1D.	IOLab	Match a described motion with x(t) and v(t) graphs     Introduction to measurement uncertainties and their propagation	Students push the IOLab up a ramp to 1. produce x(t) and v(t) graphs 2. determine the acceleration and ramp angle	Comparing obtained graphs with prediction. Start work with uncertainties.	Students construct/improvise a ramp with household items.
3		Students send IOLab in freefall. Graphical analysis yields g.	IOLab	Tutorial on data tables, graphing with error bars and interpreting linear graphs     Setting up the freefall experiment with IOLab	Drop IOLab onto a cushion from different heights     Measure time of freefall using accelerometer to plot a graph whose slope is predicted to be g/2	Constructing data tables Graphing with error bars Interpreting linear graphs	Students write discussion by filling in blanks as prompted.
4		Students launch IOLab over edge of table.	IOLab	Explore projectile motion from a horizontal platform using a simulation     Prepare and practice launching IOLab from table while taking data	Predict projectile range from table height and IOLab's speed at launch     Measure range from landing location	Uncertainty propagation Do measured result and prediction agree within uncertainty?	Students write discussion by filling in blanks as prompted.
	Acceleration on an Incline	Students roll cart down inclined track using remote control.	remote	Simulation assisted tutorial to derive "a = g sin θ", with uncertainties     Tutorial on operation of remote equipment	Predict acceleration from height and length of track     Measure acceleration from slope of v(t) graph	Uncertainty propagation Do measured result and prediction agree within uncertainty?	Students write discussion from scratch, based on experience with prior labs.
	Motion	Students swing IOLab around in circle on a string while force sensor measures tension.	IOLab	Simulation assisted tutorial on uniform circular motion     Tutorial on using IOLab force sensor	Measure period and radius to calculate speed, centripetal acceleration and force.     Measure centripetal force using force sensor	Uncertainty propagation Do measured result and prediction agree within uncertainty?	Decreasing guidance given. Students have opportunity to discuss many potential sources of error.
		Students bounce IOLab cart w/ spring bumper off a solid object.	IOLab	Students prepare and practice the collision while taking data	Change in velocity is compared to the area under F(t) graph	Interpreting v(t) and F(t) graphs for momentum and impulse	Students perform calculations and write discussion independently.
	Conservation of Mechanical Energy	Students roll IOLab as a roller coaster.	IOLab	Roller coaster simulation, with friction     Students prepare a roller coaster-like track for IOLab	IOlab is sent down track and  1. calculate total energy from height and speed data	Performing relevant calculation and comparisons with minimal guidance	Energy is usually not conserved, as seen in pre-lab simulations.
	Electron charge-to- mass ratio (e/m)	JJ Thomson's e/m experiment is performed by remote control.	remote	Orientation of equations used for analysis     Tutorial on operation of remote equipment	Measure accelerating voltage and Helmholtz coil current     Work out a value for e/m	Writing entire report from scratch, based on experience with prior labs.	Students given two weeks to complete this lab.

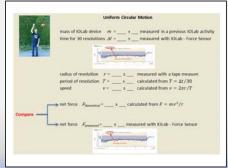
### Determining g from Freefall



### **Projectile Motion**



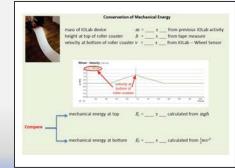
### **Uniform Circular Motion**



Plans

Future

### **Conservation of Mechanical Energy**



#### e/m - Electron Charge to Mass Ratio



Equipment located 150 km away at North Island College (Comox, Canada) are operated remotely by students through the internet.

RWSL/NANSLO facility includes lab equipment for Physics, Chemistry & Biology and are described further at http://www.nic.bc.ca/rwsl and http://www.wiche.edu/nanslo



#### **Cart on Inclined Track**



Encourage more interaction

- Peer-to-peer (e.g. online forum)
- Student-instructor (\*adjust deadline to allow last minute help - no more Sunday midnight)

Measure student outcomes

Library to manage equipment return

Lab pilot continuing 2017/18

Class portion also moving online

- Sept 2017 partially online
- Jan 2018 fully online

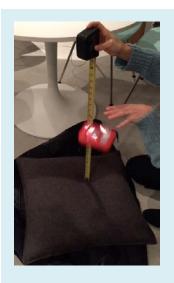
Building own remote experiments

We wish to thank the Creative Capital Fund of KPU for supporting the development of Remote and Online

Physics labs, North Island College for making remote experiments available to our students and our KPU Physics Dept. colleagues for embracing and encouraging our pilot.

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# **Determining** *g* from Freefall

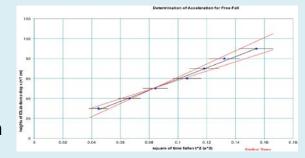
various drop distances  $x = \underline{\hspace{1cm}} \pm \underline{\hspace{1cm}}$  measured with a tape measure various drop times  $t = \underline{\hspace{1cm}} \pm \underline{\hspace{1cm}}$  measured with IOLab – Accelerometer



Initial Height of IOLab Device	Time the IOLab fell distance h
h	t
(cm)	(s)
(± 0.5 cm)	(± 3 %)
10.0	0.09369
2.6.0	0.14669
30.0	0.1116
40.0	0. 22906
50-0	0.25455
60.0	0.28117
70.0	0. 33384
80.0	0.34251
90.0	0.37702

theory predicts:  $x = \frac{1}{2}gt^2$  (since  $x_o$  and  $v_o$  both = 0)

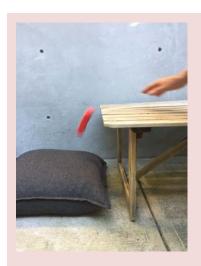
x vs.  $t^2$  graph is drawn



Compare

acceleration due to gravity  $g = \underline{\hspace{1cm}} \pm \underline{\hspace{1cm}}$  calculated from  $2 \times slope$ 

 $\Rightarrow$  acceleration due to gravity  $g = \underline{\qquad} \pm \underline{\qquad}$  looked up for particular location



# **Projectile Motion**

height of launch  $h = \underline{\hspace{1cm}} \pm \underline{\hspace{1cm}}$  measured with a tape measure horizontal launch velocity  $v = \underline{\hspace{1cm}} \pm \underline{\hspace{1cm}}$  measured with IOLab - Wheel Sensor



time of flight of projectile t= \_\_\_\_  $\pm$  \_\_\_ calculated from  $t=\sqrt{\frac{2h}{g}}$  range  $R_{theoretical}=$  \_\_\_  $\pm$  \_\_\_ calculated from R=vt

Compare

ightharpoonup range  $R_{measured} = \underline{\phantom{a}} \pm \underline{\phantom{a}}$  measured with a tape measure



## **Uniform Circular Motion**

mass of IOLab device  $m = \underline{\phantom{a}} \pm \underline{\phantom{a}}$  measured in a previous IOLab activity time for 30 revolutions  $\Delta t = \underline{\phantom{a}} \pm \underline{\phantom{a}}$  measured with IOLab - Force Sensor



radius of revolution r =\_\_\_\_  $\pm$ \_\_ measured with a tape measure period of revolution T =\_\_\_  $\pm$ \_\_ calculated from  $T = \Delta t/30$  speed v =\_\_\_  $\pm$ \_\_ calculated from  $v = 2\pi r/T$ 

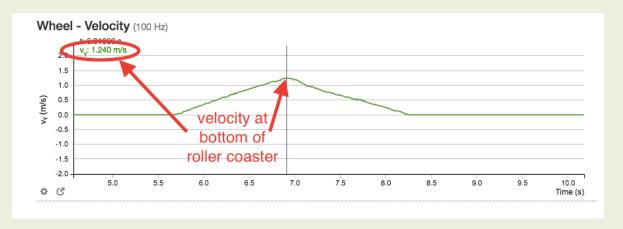
net force  $F_{theoretical} = \underline{\qquad} \pm \underline{\qquad}$  calculated from  $F = mv^2/r$ Compare  $\underline{\qquad}$  net force  $F_{measured} = \underline{\qquad} \pm \underline{\qquad}$  measured with IOLab - Force Sensor





## **Conservation of Mechanical Energy**

mass of IOLab device  $m = \underline{\hspace{1cm}} \pm \underline{\hspace{1cm}}$  from previous IOLab activity height at top of roller coaster  $h = \underline{\hspace{1cm}} \pm \underline{\hspace{1cm}}$  from tape measure velocity at bottom of roller coaster  $v = \underline{\hspace{1cm}} \pm \underline{\hspace{1cm}}$  from IOLab – Wheel Sensor



mechanical energy at top 
$$E_i = \underline{\phantom{a}} \pm \underline{\phantom{a}}$$
 calculated from  $mgh$ 

Compare

$$\rightarrow$$
 mechanical energy at bottom  $E_f = \underline{\phantom{a}} \pm \underline{\phantom{a}}$  calculated from  $\frac{1}{2}mv^2$